Advanced Tools in Macroeconomics Continuous time models (and methods)

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# Plan for today

- 1. Speeding things up while making them more robust
  - 1.1 Use the "implicit method" to somewhat bring back the contraction property
  - 1.2 Make use of sparsity
- 2. Set up a continuous time heterogenous agents model and show how to solve it

- 3. Kolmogorov Forward equation
- 4. Equilibrium

### Why is the contraction property lost?

Consider the deterministic Ramsey growth model again

$$v(k) = \max_{c} \{ u(c) + (1-\rho)v(f(k) + (1-\delta)k - c) \}.$$

In discrete time we iterate as

$$v_{n+1}(k) = \max_{c} \{ u(c) + (1-\rho)v_n(f(k) + (1-\delta)k - c) \},\$$

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• This is a contraction mapping and we know that  $v_n \rightarrow v$ .

#### Why is the contraction property lost?

Let's, heuristically, convert this into continuous time

$$v_{n+1}(k) = \max_{c} \{\Delta u(c) + (1 - \Delta \rho)v_n(k + \Delta (f(k) - \delta k - c))\}$$

$$0 = \max_{c} \{u(c) + \frac{v_n(k + \Delta(f(k) - \delta k - c)) - v_{n+1}(k)}{\Delta} - \rho v_n(k + \Delta(f(k) - \delta k - c))\}.$$

Taking limits and rearranging

$$\rho v_n(k) = \max_c \{ u(c) + \lim_{\Delta \to 0} \frac{v_n(k + \Delta(f(k) - \delta k - c)) - v_{n+1}(k)}{\Delta} \}.$$

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Why is the contraction property lost?

Problem

$$\lim_{\Delta \to 0} \frac{v_n(k + \Delta(f(k) - \delta k - c)) - v_{n+1}(k)}{\Delta} \neq v'_n(k)(f(k) - \delta - c)$$

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The right hand side of the HJB equation contains v<sub>n+1</sub> and that's a major issue

Back to discrete time

$$v_{n+1}(k) = \max_{c} \{ u(c) + (1-\rho)v_n(f(k) + (1-\delta)k - c) \},\$$

- Call the optimal choice c<sub>n</sub> (it's really a function of k but I'm saving some space)
- Howard's Improvement Algorithm says that we can then iterate on

$$v_{n+1}^{h+1}(k) = u(c_n) + (1-\rho)v_{n+1}^h(f(k) + (1-\delta)k - c_n)\},$$

with  $v_{n+1}^0 = v_n$ .

► Until v<sup>h+1</sup><sub>n+1</sub> ≈ v<sup>h</sup><sub>n+1</sub>. This can speed things up considerably, and preserves the contraction property

Suppose that it holds exactly v<sup>h+1</sup><sub>n+1</sub> = v<sup>h</sup><sub>n+1</sub>, and let's just call this function v<sub>n+1</sub>. Then it must satisfy

$$v_{n+1}(k) = \max_{c} \{ u(c_n) + (1-\rho)v_{n+1}(f(k) + (1-\delta)k - c_n) \},\$$

In ∆ units of time

$$v_{n+1}(k) = \Delta u(c_n) + (1 - \Delta \rho)v_{n+1}(k + \Delta (f(k) - \delta k - c_n)).$$

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#### Rearrange

$$0 = u(c_n) + \frac{v_{n+1}(k + \Delta(f(k) - \delta k - c_n)) - v_{n+1}(k)}{\Delta} - \rho v_{n+1}(k + \Delta(f(k) - \delta k - c_n))\}.$$

and take limits

$$\rho v_{n+1}(k) = u(c_n) + v'_{n+1}(k)(f(k) - \delta k - c_n),$$

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$$\rho v_{n+1}(k) = u(c_n) + v'_{n+1}(k)(f(k) - \delta k - c_n),$$

▶ Now the awkward discrepancy between v<sub>n+1</sub> and v<sub>n</sub> is gone!

- But the problem looks a bit hard to solve!
- Turns out it is not!
- This is where the "implicit method" comes in.

- 1. Start with a grid for capital  $\mathbf{k} = [k_1, k_2, \dots, k_N]$ .
- 2. For each grid point for capital you have a guess for  $v_0(k_i)$ ,  $\forall k_i \in \mathbf{k}$
- 3. So you have a vector of N values of  $v_0$ . Call this  $\mathbf{v}_0$
- 4. You should also have a difference operator (an  $N \times N$  matrix) **D** such that

$$\mathbf{D}\mathbf{v} pprox \mathbf{v}'(k), \quad orall k_i \in \mathbf{K}$$

5. Optimal consumption choice given by FOC

$$u'(\mathbf{c}_0) = \mathbf{D}\mathbf{v}_0$$

reasonable to call this  $c(\mathbf{v}_0)$  – an  $N \times 1$  vector

6. This implies another  $N \times 1$  vector of savings

$$\mathbf{s}_0 = (f(\mathbf{k}) - \delta \mathbf{k} - c(\mathbf{v}_0))$$

(This vector can be used to improve on  $\mathbf{D}$  – more on that in a second).

7. Create the  $N \times N$  matrix  $\mathbf{S}_0 = diag(\mathbf{s_0})$ 

That is

$$\mathbf{S} = egin{pmatrix} s_1 & 0 & \dots & 0 \ 0 & s_2 & \dots & 0 \ dots & \ddots & \ddots & dots \ 0 & \dots & 0 & s_N \end{pmatrix},$$

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8. Then our HJB equation can now be written as

$$ho \mathbf{v}_1 = u(c(\mathbf{v}_0)) + \mathbf{S}_0 \mathbf{D} \mathbf{v}_1$$

9. Manipulate

$$(\rho \mathbf{I} - \mathbf{S}_0 \mathbf{D}) \mathbf{v}_1 = u(c(\mathbf{v}_0))$$

10. Lastly

$$\mathbf{v}_1 = (\rho \mathbf{I} - \mathbf{S}_0 \mathbf{D})^{-1} u(c(\mathbf{v}_0))$$

11. Generally

$$\mathbf{v}_{n+1} = (\rho \mathbf{I} - \mathbf{S}_n \mathbf{D})^{-1} u(c(\mathbf{v}_n))$$

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Or even more generally

$$\mathbf{v}_{n+1} = ((\rho + 1/\Gamma)\mathbf{I} - \mathbf{S}_n\mathbf{D})^{-1}[u(c(\mathbf{v}_n)) + \mathbf{v}_n/\Gamma]$$

for  $\Gamma$  very large (my experience:  $\Gamma=\infty$  is fastest, but set lower if convergence issues arise)

In matlab always use backslash operator to calculate x = A<sup>-1</sup>b. I.e. x = A\b

We are talking very substantial speed/robustness gains here. Perhaps by a factor of 1,000.

# The implicit method: Improvement trick I

- Yesterday we created the matrix D as central differences
- ► We can do better. In particular, s<sub>n</sub> tells us where the economy is drifting for each k<sub>i</sub> ∈ k
- So trick one is to use forward differences for all

 $\{k_i \in \mathbf{k} : s_i > 0\}$ 

and backward differences for all

$$\{k_i \in \mathbf{k} : s_i < 0\}$$

This leads to

$$\mathbf{v}_{n+1} = ((\rho + 1/\Gamma)\mathbf{I} - \mathbf{S}_n\mathbf{D}_n)^{-1}[u(c(\mathbf{v}_n)) + \mathbf{v}_n/\Gamma]$$

# The implicit method: Improvement trick II

Inspect the matrix

$$((\rho+1/\Gamma)\mathbf{I}-\mathbf{S}_n\mathbf{D}_n),$$

and notice that all matrices are super sparse!

- So declaring them as sparse will free up a lot of memory and give you enormous speed gains too (this is particularly true for problems with N > 200 or so. Below that it doesn't really matter).
- Never declare any of these matrices as anything else than sparse! Use commands as speye and spdiags
- Don't be too concerned about loops. That doesn't seem to be what can clog these systems.

# The Aiyagari Model in Continuous Time

The rest of today's lecture will be to apply our knowledge thus far to the Aiyagari model in continuous time.

- This will also be today's exercise
- 1. Households' problem
- 2. Firms problem
- 3. Equilibrium

- Households can be employed or unemployed
- When employed they receive income  $w_t(1 \tau_t)$
- ► When unemployed they receive unemployment benefits equal to µw<sub>t</sub>
- An employed individual becomes unemployed with probability λ<sub>e</sub>.
- ► An unemployed individual becomes employed with probability \u03c6<sub>u</sub>
- ► In an Aiyagari model prices are constant:  $r_t = r$  and  $w_t = w \ \forall t$

Dynamics of aggregate unemployment

$$e_{t+1} = (1 - \lambda_e)e_t + \lambda_u u_t$$
$$u_{t+1} = \lambda_e e_t + (1 - \lambda_u)u_t$$

Δ units of time

$$e_{t+\Delta} = (1 - \Delta \lambda_e) e_t + \Delta \lambda_u u_t$$
  
 $u_{t+\Delta} = \Delta \lambda_e e_t + (1 - \Delta \lambda_u) u_t$ 

Rearrange and take limits

$$\dot{e}_t = -\lambda_e e_t + \lambda_u u_t$$
$$\dot{u}_t = \lambda_e e_t - \lambda_u u_t$$

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System

$$\dot{\mathbf{s}}_t = \mathbf{T}\mathbf{s}_t$$

with

$$\mathbf{T} = \begin{pmatrix} -\lambda_e & \lambda_u \\ \lambda_e & -\lambda_u \end{pmatrix}$$

Stationary equilibrium

$$\mathbf{0} = \mathbf{Ts}$$

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Thus s is an eigenvector associated with a zero eigenvalue, with the eigenvector normalised to sum to one.

- Can be solved as a regular eigenvalue problem
- But since the eigenvector is only defined up to a scalar we can use the following trick

1. Create vector

$$\mathbf{b} = egin{pmatrix} 1 \ 0 \end{pmatrix}$$
 and matrix  $\mathbf{\hat{T}} = egin{pmatrix} 1 & 0 \ \lambda_e & -\lambda_u \end{pmatrix}$ 

- 2. Find  $\hat{\mathbf{s}}$  as  $\hat{\mathbf{s}} = \hat{\mathbf{T}}^{-1} \mathbf{b}$ .
- 3. Normalise **ŝ** to sum to one to find **s**.
- The first element of s is then the stationary employment rate, and the second the stationary unemployment rate.

Government runs a balanced budget, so not deficits

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• The tax rate then solves  $u\mu w = e\tau w$ 

• Or just 
$$\tau = \frac{u}{e}\mu$$

Bellman equation for an employed agent

$$\begin{aligned} \mathsf{v}(\mathsf{a}_t, e) &= \max_{c_t} \{ u(c_t) + (1 - \rho) \times \\ &[(1 - \lambda_e) \mathsf{v}(w_t(1 - \tau_t) + (1 + r_t) \mathsf{a}_t - c_t, e) \\ &+ \lambda_e \mathsf{v}(w_t(1 - \tau_t) + (1 + r_t) \mathsf{a}_t - c_t, u)] \} \end{aligned}$$

subject to  $a_t \ge \phi \ \forall t$ .

Δ units of time

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• Rearrange and divide by  $\Delta$ 

$$0 = \max_{c_t} \{u(c_t) + \frac{v(\Delta(w_t(1-\tau_t)+r_ta_t-c_t)+a_t,e)-v(a_t,e)}{\Delta} + \frac{v(\Delta(w_t(1-\tau_t)+r_ta_t-c_t)+a_t,e)}{\Delta} + \lambda_e v(\Delta(w_t(1-\tau_t)+r_ta_t-c_t)+a_t,u)]\}$$

Take limits and rearrange

$$\rho v(a, e) = \max_{c} \{ u(c) + v_a(a, e)(w(1 - \tau) + ra - c) - \lambda_e(v(a, e) - v(a, u)) \}$$

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So households' problem is given by the two HJB equations

$$\rho v(a, e) = \max_{c} \{ u(c) + v_a(a, e)(w(1 - \tau) + ra - c) - \lambda_e(v(a, e) - v(a, u)) \}$$

$$\rho v(a, u) = \max_{c} \{ u(c) + v_a(a, u)(w\mu + ra - c) - \lambda_u(v(a, u) - v(a, e)) \}$$

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Let's be smart in solving them!

- 1. Start with a linearly spaced grid for assets  $\mathbf{a} = [a_1, a_2, \dots, a_N]$ . Let da = a(n+1) a(n).
- 2. For each grid for assets guess a for  $v_0(a_i, j)$ ,  $\forall a_i \in \mathbf{a}$ , and  $j \in \{e, u\}$ . This gives us  $\mathbf{v}_{0,e}$  and  $\mathbf{v}_{0,u}$

3. Call the stacked  $2N \times 1$  vector  $(\mathbf{v}_{0,e}, \mathbf{v}_{0,u})'$  for  $\mathbf{v}_0$ .

4. Create two  $N \times N$  difference operators as

$$\mathbf{D}_{\mathbf{f}} = \begin{pmatrix} -1/da & 1/da & 0 & \dots & 0 \\ 0 & -1/da & 1/da & 0 & & \\ \vdots & 0 & \ddots & \ddots & \vdots \\ \vdots & \dots & & -1/da & 1/da \\ 0 & \dots & 0 & -1 \end{pmatrix}$$

$$\mathbf{D}_{\mathbf{b}} = \begin{pmatrix} 1 & 0 & 0 & \dots & 0 \\ -1/da & 1/da & 0 & & \\ \vdots & -1/da & 1/da & \ddots & \vdots \\ \vdots & 0 & \ddots & \ddots & \vdots \\ \vdots & \dots & -1/da & 1/da \end{pmatrix}$$

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5. Create one  $2N \times 2N$  matrix as

$$\mathbf{B} = \begin{pmatrix} -\lambda_{e} & 0 & \dots & 0 & \lambda_{e} & 0 & \dots & 0 \\ 0 & -\lambda_{e} & 0 & \dots & 0 & \lambda_{e} & \dots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots & \dots & \ddots & \vdots \\ 0 & 0 & 0 & -\lambda_{e} & 0 & \dots & \dots & \lambda_{e} \\ \lambda_{u} & 0 & \dots & 0 & -\lambda_{u} & 0 & \dots & 0 \\ 0 & \lambda_{u} & 0 & \dots & 0 & -\lambda_{u} & \dots & 0 \\ \vdots & 0 & \ddots & \ddots & \vdots & \dots & \ddots & \vdots \\ 0 & 0 & 0 & \lambda_{u} & 0 & 0 & \dots & -\lambda_{u} \end{pmatrix}$$

will be used later

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6. Calculate the derivative of the value functions using both forward and backward differences

$$\begin{split} \mathbf{v}_f'(a,e) &= \mathbf{D}_{\mathbf{f}} \mathbf{v}_{0,e}, \quad \mathbf{v}_b'(a,e) = \mathbf{D}_{\mathbf{b}} \mathbf{v}_{0,e}, \\ \mathbf{v}_f'(a,u) &= \mathbf{D}_{\mathbf{f}} \mathbf{v}_{0,u}, \quad \mathbf{v}_b'(a,u) = \mathbf{D}_{\mathbf{b}} \mathbf{v}_{0,u}, \end{split}$$

- 7. Set the **first** elements of  $\mathbf{v}'_b(a, e) = u'(w(1 \tau) + r\phi)$ and  $\mathbf{v}'_b(a, u) = u'(w\mu + r\phi)$ , and the **last** elements of  $\mathbf{v}'_f(a, e) = u'(w(1 - \tau) + ra_N)$  and  $\mathbf{v}'_f(a, u) = u'(w\mu + ra_N)$
- 8. Find optimal consumption through

$$\begin{split} u'(\mathbf{c}_{e,f}) &= \mathbf{D}_{\mathbf{f}} \mathbf{v}_{0,e}, \quad u'(\mathbf{c}_{e,b}) = \mathbf{D}_{\mathbf{b}} \mathbf{v}_{0,e}, \\ u'(\mathbf{c}_{u,f}) &= \mathbf{D}_{\mathbf{f}} \mathbf{v}_{0,u}, \quad u'(\mathbf{c}_{u,b}) = \mathbf{D}_{\mathbf{b}} \mathbf{v}_{0,u}, \end{split}$$

9. Find optimal savings as

$$egin{aligned} \mathbf{s}_{e,f} &= \mathbf{w}(1- au) + r\mathbf{a} - \mathbf{c}_{e,f}, & \mathbf{s}_{e,b} &= \mathbf{w}(1- au) + r\mathbf{a} - \mathbf{c}_{e,b}, \ \mathbf{s}_{u,f} &= \mathbf{w}\mu + r\mathbf{a} - \mathbf{c}_{u,f}, & \mathbf{s}_{u,b} &= \mathbf{w}\mu + r\mathbf{a} - \mathbf{c}_{u,b} \end{aligned}$$

#### 10. Create indicator vectors

$$\mathbf{I}_{e,f} = (I_{1,e,f}, I_{2,e,f}, \dots, I_{N,e,f})', \quad \mathbf{I}_{e,b} = (I_{1,e,b}, I_{2,e,f}, \dots, I_{N,e,b})', \\ \mathbf{I}_{u,f} = (I_{1,u,f}, I_{2,u,f}, \dots, I_{N,u,f})', \quad \mathbf{I}_{u,b} = (I_{1,u,f}, I_{2,u,f}, \dots, I_{N,u,f})',$$

where  $I_{i,j,f} = 1$  if  $s_{i,j,f} > 0$  and  $I_{i,j,b} = 1$  if  $s_{i,j,b} < 0$ , for i = 1, ..., N and  $j \in \{e, u\}$ .

11. Find consumption as

$$\mathbf{c}_{e} = \mathbf{I}_{e,f} \cdot \mathbf{c}_{e,f} + \mathbf{I}_{e,b} \cdot \mathbf{c}_{e,b}$$
$$\mathbf{c}_{u} = \mathbf{I}_{u,f} \cdot \mathbf{c}_{u,f} + \mathbf{I}_{u,b} \cdot \mathbf{c}_{u,b}$$

12. Find savings as

$$\mathbf{s}_{e} = \mathbf{I}_{e,f} \cdot \mathbf{s}_{e,f} + \mathbf{I}_{e,b} \cdot \mathbf{s}_{e,b}$$
$$\mathbf{s}_{u} = \mathbf{I}_{u,f} \cdot \mathbf{s}_{u,f} + \mathbf{I}_{u,b} \cdot \mathbf{s}_{u,b}$$

13. And matrices  $\mathbf{S}_{e}\mathbf{D}_{e}$  and  $\mathbf{S}_{u}\mathbf{D}_{u}$  as

$$\begin{split} \mathbf{S}_{e}\mathbf{D}_{e} &= diag(\mathbf{I}_{e,f} \cdot \mathbf{s}_{e,f})\mathbf{D}_{f} + diag(\mathbf{I}_{e,b} \cdot \mathbf{s}_{e,b})\mathbf{D}_{b} \\ \mathbf{S}_{u}\mathbf{D}_{u} &= diag(\mathbf{I}_{u,f} \cdot \mathbf{s}_{u,f})\mathbf{D}_{f} + diag(\mathbf{I}_{u,b} \cdot \mathbf{s}_{u,b})\mathbf{D}_{b} \end{split}$$

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14. Lastly find the  $2N \times 2N$  matrix  $\mathbf{S}_0 \mathbf{D}_0$  as

$$\mathbf{S}_0 \mathbf{D}_0 = egin{pmatrix} \mathbf{S}_e \mathbf{D}_e & \mathbf{0} \ \mathbf{0} & \mathbf{S}_u \mathbf{D}_u \end{pmatrix}$$

15. And the matrix  $\mathbf{P}_0$  as

$$\mathbf{P}_0 = \mathbf{S}_0 \mathbf{D}_0 + \mathbf{B}$$

Using the implicit method the households' problem is given by the two HJB equations

$$\rho v_{n+1}(a, e) = u(c_n) + v_{a,n+1}(a, e)(w(1 - \tau) + ra - c_n) \\ - \lambda_e(v_{n+1}(a, e) - v_{n+1}(a, u))$$

$$\rho v_{n+1}(a, u) = u(c_n) + v_{a,n+1}(a, u)(w\mu + ra - c) 
- \lambda_u(v_{n+1}(a, u) - v_{n+1}(a, e))$$

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These can now be written as

$$\rho \mathbf{v}_{n+1} = u(\mathbf{c}_n) + \mathbf{P}_n \mathbf{v}_{n+1}$$

with  $\mathbf{c}_n = (\mathbf{c}_{n,e}, \mathbf{c}_{n,u})$ .

So we iterate on

$$\mathbf{v}_{n+1} = [(
ho + 1/\Gamma)\mathbf{I} - \mathbf{P}_n]^{-1}[u(\mathbf{c}_n) + \mathbf{v}_n/\Gamma]$$

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until convergence

# Firms

Firms fact the standard static optimisations problem

$$\Pi_t = \max\{K_t^{\alpha} N_t^{1-\alpha} - w_t N_t - (r_t + \delta) K_t\}$$

With first order conditions

$$r_t = \alpha \left(\frac{K_t}{N_t}\right)^{\alpha-1} - \delta, \quad w_t = (1-\alpha) \left(\frac{K_t}{N_t}\right)^{\alpha}$$

In a stationary equilibrium this implies

$$r = \alpha \left(\frac{\kappa}{(1-u)}\right)^{\alpha-1} - \delta, \quad w = (1-\alpha) \left(\frac{r+\delta}{\alpha}\right)^{\frac{\alpha}{\alpha-1}}$$

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#### Stationary distribution

- What is the evolution of the endogenous stationary distribution of wealth and employment status?
- Denote the CDF as  $G_{t+1}(a, e)$ . This must satisfy

$$G_{t+1}(a,e) = (1-\lambda_e)G_t(a_{-1}^e,e) + \lambda_u G_t(a_{-1}^u,u),$$

where  $a_{-1}^{j}$  denotes "where you came from" from optimally setting  $a_{t+1} = a$  in employment status  $j \in \{e, u\}$ .

In ∆ units of time approximate this as a<sup>e</sup><sub>-1</sub> = a − ∆s<sub>e</sub> and a − ∆s<sub>u</sub>. Thus

$$G_{t+\Delta}(a,e) = (1 - \Delta \lambda_e)G_t(a - \Delta s_e, e) + \Delta \lambda_u G_t(a - \Delta s_u, u),$$

# Stationary distribution

$$G_{t+\Delta}(a,e) = (1-\Delta\lambda_e)G_t(a-\Delta s_e,e) + \Delta\lambda_u G_t(a-\Delta s_u,u),$$

Subtract  $G_t(a, e)$  from both sides and divide by  $\Delta$ 

$$\frac{G_{t+\Delta}(a,e) - G_t(a,e)}{\Delta} = \frac{G_t(a - \Delta s_e, e) - G_t(a,e)}{\Delta} - \lambda_e G_t(a - \Delta s_e, e) + \lambda_u G_t(a - \Delta s_u, u),$$

Take limits

$$\dot{G}_t(a,e) = -g_t(a,e)s_e(a) - \lambda_e G_t(a,e) + \lambda_u G_t(a,u),$$

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Stationary distribution/Kolmogorov Forward Equation

$$G_t(a, e) = -g_t(a, e)s_e(a) - \lambda_e G_t(a, e) + \lambda_u G_t(a, u),$$

Differentiate with respect to a

$$\dot{g}_t(a, e) = -\frac{\partial [g_t(a, e)s_e(a)]}{\partial a} - \lambda_e g_t(a, e) + \lambda_u g_t(a, u),$$

Thus the law of motion for the endogenous distribution is

$$\dot{g}_t(a, e) = -\frac{\partial [g_t(a, e)s_e(a)]}{\partial a} - \lambda_e g_t(a, e) + \lambda_u g_t(a, u),$$
  
$$\dot{g}_t(a, u) = -\frac{\partial [g_t(a, u)s_u(a)]}{\partial a} - \lambda_u g_t(a, u) + \lambda_e g_t(a, e)$$

# Stationary distribution/Kolmogorov Forward Equation

Remember the matrix

$$\mathsf{P}_n = \mathsf{S}_n \mathsf{D}_n + \mathsf{B}.$$

When converged

$$\mathbf{P}=\mathbf{S}\mathbf{D}+\mathbf{B}$$

Turns out that

$$\dot{\mathbf{g}}_t = \mathbf{P}' \mathbf{g}_t$$

• Where  $\mathbf{g}_t$  is the stacked vector  $(\mathbf{g}_t(a, e), \mathbf{g}_t(a, u))'$ 

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# Solving the Aiyagari model

1. Guess for an interest rate  $r_n$ . Find  $w_n$  as

$$w_n = (1 - \alpha) \left(\frac{r_n + \delta}{\alpha}\right)^{\frac{\alpha}{\alpha - 1}}$$

2. Find  $\mathbf{v}$  such that

$$\mathbf{v} = [(
ho + 1/\Gamma)\mathbf{I} - \mathbf{P}]^{-1}[u(c(\mathbf{v})) + \mathbf{v}/\Gamma]$$

3. Find g by solving

$$\mathbf{0} = \mathbf{P}'\mathbf{g}$$

and normalise to sum to one (remember how we found  ${f s}$  above)

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Solving the Aiyagari model

4. Find  $K_n$  as

$$\mathcal{K}_n = \mathbf{g}' \begin{pmatrix} \mathbf{a} \\ \mathbf{a} \end{pmatrix}$$

5. Find  $\hat{r}$  as

$$\hat{r} = \alpha \left(\frac{K_n}{(1-u)}\right)^{\alpha-1} - \delta$$

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6. If  $\hat{r} > r$  set  $r_{n+1} > r_n$ , else set  $r_{n+1} < r_n$ . 7. Repeat until  $\hat{r} \approx r_n$ .